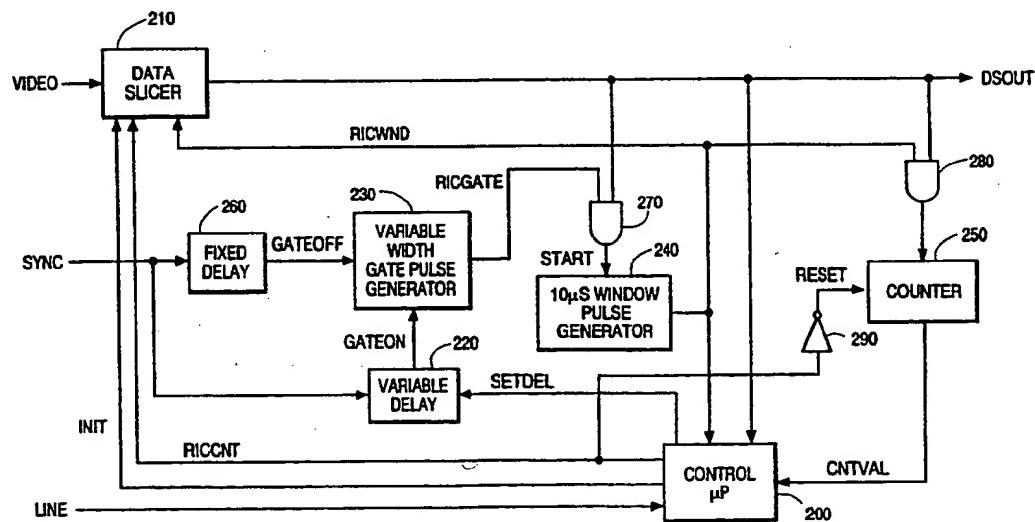


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(54) Title: AUXILIARY VIDEO DATA DECODER WITH LARGE PHASE TOLERANCE



(57) Abstract

An auxiliary video information decoder, for decoding auxiliary video information signals such as closed caption data, includes a data slicer (210) having a variable slicing level. The slicing level is adjusted in response to the amplitude of a run-in-clock (RIC) signal that is included in the auxiliary video information portion of the video signal. Slicing level adjustment involves averaging the RIC signal amplitude during a substantially integral number of cycles of the RIC signal that occur during a control interval (RICWND). The timing of the RIC signal waveform with respect to the control interval is evaluated to verify that the desired number of cycles of the RIC signal occur during a control interval. The timing evaluation operation involves counting (250) cycles of the RIC signal during a control interval. If the desired number of cycles do not occur, the timing of the control interval is modified (200, 220, 230) with respect to the RIC signal and the timing is reevaluated during a subsequent control interval. The evaluation and timing-modification operations may be repeated until the desired number of cycles of the RIC signal are detected. If repeated operation does not provide the desired result, a control signal may be generated indicating that the video signal may not include auxiliary video information.

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AUXILIARY VIDEO DATA DECODER WITH LARGE PHASE TOLERANCE

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Field of the Invention

The present invention relates to detection of information that may be present in a video signal during vertical blanking intervals.

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Background of the Invention

A video signal typically includes vertical display intervals, or fields, having a plurality of horizontal line intervals, e.g. 262.5 lines per field in NTSC video systems. The beginning of each vertical and horizontal interval is identified by respective vertical and horizontal sync pulses that are included in a composite video signal. During a portion of each vertical interval, information in the video signal may not be intended for display. For example, a vertical blanking interval spans approximately the first 20 horizontal line intervals in each field. In addition, several line intervals adjacent to the vertical blanking period, e.g. line 21, may be within an overscan region of a video display and will not be visible.

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The lack of displayed image information during blanking and overscan intervals makes it possible to insert an auxiliary information component, e.g. teletext or closed caption data, into these intervals. Standards such as Federal Communications Commissions (FCC) Regulations define the format for each type of auxiliary information including the positioning of the information within a vertical interval. For example, the present closed captioning standard (see e.g. 47 CFR §§ 15.119 and 73.682) specifies that digital data corresponding to ASCII characters for closed captioning must be in line 21 of field 1.

The first step in extracting auxiliary video information is to locate the auxiliary information. Various approaches may be used depending on the type of information involved. For example, recognition of teletext data characteristics such as the framing code pattern is a method of locating teletext data. Closed caption information in line 21 may be located by counting video lines, e.g. counting horizontal sync pulses.

After the auxiliary video information is located, the information must be extracted. In the case of digital data, a "data slicer" may be used to convert the video signal into binary data.

A data slicer typically operates by comparing the video signal level to a reference level known as the slicing level. For video levels that exceed the slicing level, the comparison produces a logic 1. Video levels that are less than the slicing level produce a logic 0. As an example, closed caption data in line 21 of the video signal may exhibit a signal amplitude range of 0 IRE to 50 IRE. For a signal range of 0 IRE to 50 IRE, a slicing level of 25 IRE would be appropriate.

A constant slicing level may not be adequate for all video signals. Video signal levels may vary depending on the source of the video signal. Utilizing a constant slicing level with varying video signal levels may bias the extracted data undesirably toward logic 0 or logic 1 resulting in erroneous data extraction. For example, if the video signal range is 0 IRE to 20 IRE rather than 0 IRE to 50 IRE, a slicing level of 10 IRE rather than 25 IRE is desirable. If 25 IRE were used as a slicing level for a signal range of 0 IRE to 20 IRE, a logic 1 would never be extracted because the signal never exceeds the slicing level. Thus, it is desirable to adapt the slicing level to the amplitude of the input video signal.

The format of an auxiliary information component such as closed caption data includes provisions to facilitate an adaptive slicing level function. As specified in the FCC standards, a closed caption signal in line 21 begins after the "back porch" interval of the video signal with a 7 cycle burst of a sinusoidal

reference waveform designated the "run-in clock" (RIC). The RIC reference component of the auxiliary video data signal is followed in the latter half of the line 21 interval by a data signal component that represents the actual closed caption data. The 5 closed caption data standard establishes that the amplitude of the RIC signal is identical to the amplitude of the data signal. Thus, the average of the RIC signal amplitude is an appropriate slicing level for the subsequent data signal.

An approach to establishing a slicing level based on 10 the RIC signal amplitude is disclosed in U.S. Patent Application Serial No. 850,199 by E. Rodriguez-Cavazos et al. As disclosed by Rodriguez-Cavazos et al., a slicing level is adjusted to correspond to the average value of the RIC signal amplitude during an interval spanning a substantially integral number of cycles of the 15 RIC signal. The desired interval is defined by creating an averaging window that spans a portion of the RIC signal. For example, FCC specifications for closed caption data (see e.g. 47 CFR §§ 15.119 and 73.682) dictate that 7 cycles of a 503 kHz RIC waveform will occur within the RIC signal interval. The duration 20 of one cycle and the RIC interval are approximately 2 μ s and 14 μ s, respectively. Therefore, as suggested by Rodriguez-Cavazos et al., a 10 μ s wide window centered within the RIC interval spans a substantially integral number of cycles, namely approximately 5, as desired. The average value of the amplitude of the RIC 25 waveform during the window is the desired slicing level.

Establishing an accurate slicing level based on the RIC signal requires accurately locating the RIC signal within a line interval that contains auxiliary video data. FCC specifications for closed caption data specify that the RIC signal will begin at 30 approximately 10 μ s and end at approximately 24 μ s after the leading (falling) edge of the horizontal sync pulse for line 21 of field 1. The FCC specification would appear to permit using a fixed delay from the horizontal sync pulse to accurately locate the RIC signal as required. For example, in the system disclosed by 35 Rodriguez-Cavazos et al., a 10 μ s window beginning following a 12

μ s delay from the leading edge of horizontal sync spans the time interval from 12 μ s to 22 μ s after the leading edge of horizontal sync. This window placement is centered within the RIC signal occurring between 10 μ s and 24 μ s after the leading edge of 5 horizontal sync and would, therefore, encompass a substantially integral number of cycles of the RIC signal.

The described delay approach to locating the RIC signal depends on signal timing that complies precisely with FCC specified values for a composite video signal. In television 10 systems, various versions of horizontal sync signals may be generated. For example, a sync separator may provide sync signals from the composite video signal while a horizontal phase-locked loop (PLL) may produce a uniform sync waveform for deflection purposes. Generating the sync separator output from 15 composite video insures that the sync separator signal is synchronized with the timing of the actual video information in the composite video signal. Under typical conditions, the timing of the horizontal PLL waveform is also synchronized with composite video. Under typical conditions, therefore, either source of sync 20 signals might provide an accurate timing reference for locating a RIC signal within the video signal.

Certain video sources may, however, cause brief but significant timing differences to exist between the composite video sync signal and the output of the horizontal PLL. For 25 example, switching between multiple video read heads in a video cassette recorder (VCR) may produce an abnormal horizontal line period that differs significantly from the nominal 64 μ s period. The deviation in the line period may produce a perturbation in the horizontal PLL that is manifested as a substantial phase shift 30 between the composite sync signal at the sync separator output and the horizontal pulse waveform at the horizontal PLL output. The locking action of the PLL gradually corrects the perturbation such that the phase error is substantially eliminated before visible display begins. A significant phase shift may exist, however, for 35 line periods within vertical blanking and overscan intervals. At

line 21, for example, a phase shift on the order of 10 μ s may exist. As a result, the actual timing of information in line 21 as indicated by the sync separator output differs from the timing indicated by the output of a horizontal PLL. Thus, while the sync separator 5 output accurately indicates the video signal timing for line 21, the horizontal PLL output may not.

The preceding discussion indicates that the sync separator output is the preferred timing reference for purposes of locating the RIC signal in line 21. However, system constraints 10 may dictate that a horizontal sync signal from the horizontal PLL must be used as a timing reference. In this situation, phase shifts between the horizontal PLL output and the video may make location of the RIC signal unreliable possibly causing an inaccurate data slicing level and subsequent corruption of extracted auxiliary 15 data.

Summary of the Invention

In accordance with the principles of the present 20 invention, an auxiliary video information decoder for decoding auxiliary video information signals includes a data slicer having an adjustable threshold level. The threshold level is adjusted in response to the periodically varying amplitude of a reference component of the auxiliary video information signal. Threshold 25 level adjustment occurs during a control interval. The timing of the control interval can be adjusted with respect to the timing of the reference component to cause the control interval to encompass a substantially integral number of cycles of the RIC signal.

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Brief Description of the Drawing

Figure 1 shows an example of an auxiliary video data waveform.

Figure 2 shows, in block diagram form, an embodiment of the invention.

Figure 3A and 3B show flowcharts useful for understanding the operation of the embodiment in Figure 2.

5 Figures 4 and 5 show signal waveforms useful for understanding the operation of the embodiment in Figure 2.

Detailed Description of the Drawing

10 The operation of an exemplary embodiment of the invention as shown in Figure 2 will be explained in the context of closed caption data that complies with the FCC standard closed caption signal depicted in Figure 1. As discussed further below, the invention is also applicable to the extraction of other forms of
15 auxiliary video data such as teletext.

In Figure 2, a composite video signal VIDEO is input to data slicer 210. Data slicer 210 converts auxiliary video data, e.g. closed caption data, included in signal VIDEO into a digital data stream identified in Figure 2 as signal DSOUT. Logic 0 and logic 1
20 levels in signal DSOUT represent levels of signal VIDEO that are less than and exceed, respectively, a slicing level maintained within data slicer 210. The slicing level is generated by data
slicer 210 under control of microprocessor 200.

As discussed above, an example of a data slicer
25 arrangement suitable for implementing data slicer 210 is described in US Patent Application Serial No. 850,199 by Rodriguez-Cavazos et al. The data slicer disclosed by Rodriguez-Cavazos et al. establishes a slicing level equal to the average amplitude of a run-in clock (RIC) signal during a window interval
30 that is coincident with the occurrence of the RIC signal. As described further below, the system in Figure 2 operates to establish timing coincidence of a window interval and the RIC signal by executing the procedure shown in Figure 3.

The operation of the system depicted in Figures 2 and
35 3 may be initiated in response to a variety of situations. For

example, activating a new source of signal VIDEO may require verifying the accuracy of the slicing level. As described above, a signal source such as a video cassette recorder (VCR) may produce timing inconsistencies sufficient to cause potential slicing level 5 errors in data slicer 210. Alternatively, periodic verification of the timing associated with the slicing level determination may be desirable to insure that factors such as component aging or environmental conditions (e.g. heat, noise, etc.) have not adversely affected system timing. Figure 2 does not show a signal activating 10 the disclosed system.

When microprocessor 200 receives a stimulus (e.g. a periodic event or new video source selection) activating the system shown in Figure 2, microprocessor 200 performs the routine depicted in Figures 3A and 3B. First, microprocessor 200 15 initializes the slicing level (step 300 in Figure 3A) in data slicer 210 to a value exceeding the maximum anticipated auxiliary video data signal range on signal VIDEO. Slicing level initialization is accomplished via control signal INIT in Figure 2. For example, the slicing level in data slicer 210 may be forced to a suitably high 20 value via a pullup network activated by signal INIT. Establishing a slicing level that exceeds the maximum input signal range insures that no transitions will appear initially on signal DSOUT because the input signal transitions will never cross the slicing level.

25 Following initialization of the slicing level at step 300, the system waits at step 305 until a line 21 of signal VIDEO occurs as indicated by signal LINE from a line counter (not shown in Figure 2). Various line counter implementations are known.

When line 21 is detected at step 305, microprocessor 30 200 monitors signal DSOUT during line 21 (step 310) to determine if a transition occurs on signal DSOUT. If a transition is not detected, the slicing level in data slicer 210 is decreased a predetermined amount at step 345 under control of signal RICCNT from microprocessor 200. For example, in the data slicer 35 arrangement disclosed by Rodriguez-Cavazos et al., a switchable

feedback circuit is activated to adjust the slicing level. Activating the feedback circuit when the slicing level is at a value exceeding the maximum data value, e.g. at step 300, causes the slicing level to decrease. The decrease of slicing level at step 345 may, 5 therefore, be accomplished by activating the feedback circuit under control of signal RICCNT. A predetermined amount of slicing level decrease may be achieved by activating the feedback circuit for a predetermined time. For example, microprocessor 200 may test for a transition on signal DSOUT (step 310) during 10 the first half of a line 21 interval when the RIC signal is expected to occur and, if a transition is not detected, the slicing level may be decreased (step 345) during the latter half of the line 21 interval.

Steps 305, 310, and 345 are repeated until a transition 15 is detected on signal DSOUT during a line 21 interval. Detection of a transition is presumed to represent the presence of data rather than noise because the slicing level is being decreased from a high value when a transition is detected. As a result, large amplitude data pulses will cross the slicing level to cause an output 20 transition before the slicing level decreases sufficiently to enable low amplitude signals or horizontal sync pulses to cause an output transition.

As described below, detection of RIC signal peaks serves to verify timing coincidence between a window interval 25 and the RIC signal. When the window is coincident with the RIC signal, adjusting the slicing level during the window interval will cause the slicing level to be equal to the average amplitude of the RIC signal as desired. Accurate extraction of auxiliary video data will then be possible.

30 Detection of a transition on signal DSOUT at step 310 results in variable STAGE being set to a value of 1 at step 315. As explained below, the routine shown in Figures 3A and 3B may involve as many as three stages of operation. Stage 1 is always executed while stages 2 and 3 may not be required. The value of

variable STAGE indicates which stage of operation is being executed.

Each stage begins at step 320 in Figure 3A. The operation of the system in Figure 2 during step 320 is shown in 5 more detail in Figure 3B. In general, the operation depicted in Figures 3A and 3B involves adjusting the slicing level during a window interval for each stage of operation. The timing of the window interval with respect to the video signal is different in each stage of operation. After the slicing level is adjusted, the 10 output of the slicer is tested to determine whether the timing set for the window interval is producing a desired slicing level.

The procedure begins at step 3201 in Figure 3B where microprocessor 200 initiates a timeout period. The purpose of the timeout period is to provide an interval at the beginning of each 15 stage of operation during which slicing level adjustment occurs.

The slicing level that is produced may not be the desired value (e.g. average of the RIC signal amplitude) if the timing of the window interval with respect to the video signal is not correct. However, initially the slicing level that is produced is not 20 important because the validity of the slicing level will be tested later in the routine as described below. What is important during the timeout period is to establish a stable slicing level. Thus, the timeout period must be of sufficient duration to insure that the slicing level has stabilized. The duration of the timeout period 25 may vary depending on the implementation of data slicer 210 that is selected. For a data slicer such as that disclosed by Rodriguez-Cavazos et al., a timeout period of 1 second is appropriate.

After the timeout period is initiated at step 3201, 30 signal RICCNT is set to logic 0 at step 3202. As shown in Figure 2, signal RICCNT controls two functions: counter 250 and data slicer 210. Counter 250 will be used as described below to count pulses on signal DSOUT as part of the test of the timing of the slicing level adjustment window interval. When signal RICCNT is at logic 0, 35 signal RESET is set to logic 1 via inverter 290 causing counter 250

to be disabled. Signal RICCNT at logic 0 enables the slicing level adjustment feature of data slicer 210. When signal RICCNT is at logic 1, counter 250 is enabled while slicing level adjustment is disabled in data slicer 210. Possible problems with simultaneous enabling of the counter and data slicer are discussed in more detail in the above-identified application by Rodriguez-Cavazos et al.

Disabling the counter (enabling of slicing level adjustment) at step 3202 is followed at step 3203 by a halt until a line that is expected to contain auxiliary video information, e.g. line 21 in field 1 for closed caption data, is detected. Microprocessor 200 then tests at step 3204 to see if the timeout period has ended. If the test fails, the routine continues at step 3206. If the timeout period has ended, indicating that slicing level adjustment is complete, signal RICCNT is set to logic 1 at step 3205 to enable counter 250 and the routine continues at step 3206.

At step 3207, gate pulse generator 230 generates a variable width gate interval pulse on signal RICGATE. As described further below, the variable width feature of the gate interval pulse serves to adjust the timing of the slicing level adjustment window with respect to the video signal. The variable width feature is created by varying the delay of the start of the gate interval pulse (step 3206) with respect to the leading edge of signal SYNC while the end of the gate interval pulse is fixed with respect to the leading edge of signal SYNC. The gate interval pulse begins in response to signal GATEON from variable delay unit 220. The delay of signal GATEON with respect to the leading edge of signal SYNC may be varied by variable delay unit 220 to position the start of the gate interval pulse as desired. The end of the gate interval pulse is defined by signal GATEOFF that occurs a fixed delay (e.g. 32 μ s) after the leading edge of signal SYNC. The fixed delay is generated by fixed delay unit 260 in Figure 2. The RICGATE signal waveforms shown in Figure 4 depict the variable start delay and fixed end delay of the

gate interval pulse. Signals GATEON and GATEOFF are not shown in Figure 4.

The delay value provided by variable delay unit 220 at step 3206 is established by signal SETDEL from microprocessor 5 200. A different delay value is set at step 3206 for each stage of operation in the routine shown in Figure 3B. The delay values shown in Figure 3B, namely 8 μ s for stage 1, 16 μ s for stage 2, and 0 μ s for stage 3, were selected for reasons explained below. The pulse width values shown at step 3207 assume that the gate pulse 10 ends after a fixed delay of 32 μ s (from fixed delay unit 260) after the leading edge of signal SYNC. Subtracting the delay values shown at step 3206 from the fixed delay of 32 μ s gives the pulse width values of 24 μ s, 16 μ s, and 32 μ s for stages 1, 2, and 3, respectively, that are listed at step 3207. RICGATE waveforms 15 demonstrating pulse widths of 24 μ s, 16 μ s, and 32 μ s are shown in Figures 4A, 4B, and 4C, respectively.

At step 3208, the first transition on signal DSOUT during the gate interval pulse generated at step 3207 causes a 10 μ s window pulse to be generated on signal RICWND by window 20 pulse generator 240. Window pulse generation is triggered by signal START at the output of AND gate 270. Signal START is the logical AND of signal RICGATE and signal DSOUT. Thus, transitions on signal DSOUT appear on signal START during the gate interval pulse on signal RICGATE. Window pulse generator 240 should be 25 a "one-shot" design to insure that only one 10 μ s pulse is generated on signal RICWND during any one gate interval pulse on signal RICGATE.

The 10 μ s window pulse defines an interval during which either the slicing level is adjusted if signal RICCNT is at logic 30 0 or pulses on signal DSOUT are counted if signal RICCNT is at logic 1. At step 3209, the value of signal RICCNT is tested. If signal RICCNT is not at logic 1, slicing level adjustment occurs during the window interval as indicated at step 3210. Steps 3203 through 3210 are repeated as described above until the timeout period 35 has expired as determined at step 3204. When the timeout period

has ended, the slicing level is presumed to have stabilized and signal RICCNT is set to logic 1 at step 3205. The subsequent test of the value of signal RICCNT at step 3209 will produce a successful result and execution will continue at step 370 in Figure 5 3A rather than at step 3210 in Figure 3B.

As mentioned above, a 10 μ s window pulse can span approximately five complete cycles of the RIC waveform. However, as shown in Figure 1, only 7 cycles of the RIC signal occur in any one line 21. Thus, as can be seen from Figure 4(A), a 10 timing displacement between the window on signal RICWND and the RIC signal will cause at least a portion of the seven cycles of RIC to fall outside the window. A significant timing shift will result in significantly fewer than five cycles of RIC during the window interval. In addition, the number of cycles within the 15 window may not be an integral number of cycles. Thus, an accurate slicing level may not be produced by slicing level generation approaches, that adjust the slicing level during a substantially integral number of cycles of the RIC signal.

The position of the window with respect to the RIC 20 signal may be verified by counting the number of cycles of RIC that occur during the window. For example, assuming that auxiliary video data exists in the video signal, a count unequal to five indicates that five cycles of RIC did not occur during a 10 μ s window and that a significant window positioning error exists. 25 The described counting operation is performed at step 370 by counter 250.

At step 370 in Figure 3A, pulses that occur on signal DSOUT during the window interval are counted by counter 250. Counter 250 is kept in a cleared state by signal RESET as long as 30 signal RICCNT is at logic 0 (slicing level adjustment enabled). After signal RICCNT is set to logic 1 at step 3205 in Figure 3B to enable counting (slicing level adjustment disabled), counting will occur only during the window pulse interval because the clock signal for counter 250 is provided by the output of AND gate 280 35 which gates signal RICWND with signal DSOUT. Thus, pulses on

signal DSOUT during the window interval will clock counter 250. The number of pulses will be represented by count value CNTVAL at the end of the window interval.

At the end of the window interval, count value
5 CNTVAL from counter 250 is evaluated by microprocessor 200 at step 335. Pulses counted by counter 250 may represent either cycles of the RIC signal or other signal transitions that cross the slicing level. However, if value CNTVAL equals five, five cycles of the RIC are presumed to have been detected during the window
10 interval. The probability that a signal other than RIC might include exactly five pulses that cross the slicing level during the window interval is negligibly low. Thus, the detection of five RIC cycles during the window indicates that signal SYNC is correctly synchronized with signal VIDEO as shown in Figure 4(A) and the
15 routine in Figure 3A is exited (step 360).

If value CNTVAL is not equal to five at step 335, either auxiliary video data does not exist (the transitions detected at steps 310 and 365 were produced by non-RIC data) or a timing error exists between signals VIDEO and SYNC that could not be
20 corrected by stage 1 operation. In either case, a second stage of the procedure is entered (steps 355, 350, and 320) to attempt to eliminate the timing error.

The operation of the system during stage 1 as depicted in Figure 3 will adapt the window timing to overcome substantial
25 timing shifts between signals SYNC and VIDEO. For example, consider modifying the situation depicted in Figure 4(A) (no timing shift) such that signal VIDEO leads signal SYNC by approximately 5 μ s. The modified timing is depicted in Figure
5(A). As shown in Figure 5(A), the RIC signal begins
30 approximately 5 μ s after the rising edge of signal SYNC rather than at 10 μ s as shown in Figure 4(A). The described timing is such that at least one complete cycle of RIC will occur prior to the gate interval pulse beginning at 8 μ s after the rising edge of SYNC. However, approximately 6 cycles of RIC will occur during the
35 beginning of the gate interval pulse. The window pulse on signal

RICWND will begin immediately upon the occurrence of the first output signal transition within the gate interval which corresponds to the first pulse of RIC within the gate interval. As a result, of the approximately 6 cycles of RIC within the gate

5 interval, 5 will occur within the window pulse interval as desired.

If signal VIDEO leads signal SYNC by significantly more than 5 μ s, e.g. 8 μ s, fewer than 5 cycles of RIC will occur during the window interval despite the timing adaptation capabilities of stage 1 operation. This situation is depicted in Figure 5(B). As a 10 result, value CNTVAL will not equal 5 and the test of value CNTVAL (step 335 in Figure 3) will fail. Without additional measures, the failure of the test of CNTVAL would indicate that auxiliary video data did not exist. Stage 1 operation alone, therefore, is unable to adapt the signal timing to detect auxiliary 15 video data and locate the RIC signal as required for timing conditions where signal VIDEO leads signal SYNC by greater than 8 μ s. However, the above-described VCR operation may cause signal VIDEO to lead signal SYNC by 10 μ s or more at line 21. Thus, timing adaptation capabilities beyond stage 1 may be required.

20 Stage 3 as described below is included in the routine depicted in Figure 3 to address extreme cases of signal VIDEO leading signal SYNC.

For the case where signal VIDEO lags signal SYNC, stage 1 operation can potentially correct for significantly greater timing 25 shifts than the above-described situation where signal VIDEO leads signal SYNC. For stage 1 operation as depicted in Figure 4(A), the 24 μ s wide gate interval pulse ends 32 μ s after the rising edge of SYNC. The 10 μ s window pulse may begin anywhere within the 24 μ s period of the gate pulse in response to the first 30 transition within the gate interval. The end of the gate interval pulse does not terminate the window pulse. As a result, a RIC signal beginning as late as 30 μ s after the rising edge of SYNC (corresponding to approximately a 20 μ s lag of signal VIDEO after signal SYNC) would produce a transition within the window 35 interval, thereby initiating a window pulse before the end of the

gate interval. For this timing condition (see Figure 5(C)), five of the 7 cycles of RIC fall within the window interval as desired. It would appear, therefore, that stage 1 operation can adapt the window timing to conditions as extreme as signal VIDEO lagging 5 signal SYNC by 20 μ s.

Characteristics of signal VIDEO may, however, prevent stage 1 from operating as described when signal VIDEO lags signal SYNC by more than the delay value between the rising edge of signal SYNC and the start of the gate interval (8 μ s delay for stage 10 1 as shown in Figure 4(A)). In the exemplary timing of Figure 4(A), if signal VIDEO lags signal SYNC by more than 8 μ s, the end of line 20 in signal VIDEO will extend into the gate interval pulse. This situation is shown in Figure 5(D). Signal transitions at the end of line 20 within the gate interval may cross the slicing level 15 causing data slicer 210 to produce pulses at the beginning of the gate interval. Pulses caused by video data from line 20 will initiate the window interval rather than the RIC pulses from line 21. As a result, the positioning of the window interval will be related to the video data from line 20, not the RIC signal from line 20 21 as desired.

If transitions of video data from line 20 trigger the window pulse, pulses during the window interval will be caused by video data from line 20, not RIC pulses from line 21 because a 10 μ s window interval initiated at the end of line 20 cannot 25 overlap a RIC signal that begins at least 10 μ s after the end of line 21. Although pulses that occur during the window interval in response to line 20 data will be counted by counter 250, it is unlikely that the resulting value CNTVAL would equal exactly 5 and satisfy the test at step 335 of Figure 3. Therefore, any video 30 data transitions in line 20 that cross the slicing level during the gate interval may cause the test of value CNTVAL (step 335) to fail independent of the existence of auxiliary video data in line 21.

Stage 1 operation alone may, therefore, be unable to adjust the window timing as required to detect auxiliary video 35 data and locate the RIC signal if signal VIDEO lags signal SYNC at

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line 21 by an amount exceeding 8 μ s. Measurements have shown that the above-described VCR operation may cause signal VIDEO to lag signal SYNC by more than 10 μ s at line 21. As described below, stage 2 has been included to address this situation.

5 To briefly summarize the preceding discussion, at the end of stage 1, if the test of CNTVAL at step 335 fails (unequal to 5), three conditions may exist: signal VIDEO lags signal SYNC by more than 8 μ s; signal VIDEO leads signal SYNC by more than 8 μ s; or no auxiliary data exists in line 21 of signal VIDEO. The first of
10 these possibilities (lag) is addressed in stage 2 following stage 1. If stage 2 fails to produce a CNTVAL value of 5, the second possibility (lead) is tested in stage 3. An incorrect CNTVAL value after stage 3 produces a "no auxiliary video data" indication at step 360.

15 Stage 2 is entered by a return to step 320 in Figure 3 after variable STAGE is incremented at step 350. In stage 2, the timing of signal VIDEO is presumed to lag the timing of signal SYNC. This situation is shown in Figure 4(B). The routine executed during stage 2 is identical to that shown in Figures 3A
20 and 3B for stage 1 except that the delay produced by delay generator 220 is set to 16 μ s (rather than 8 μ s as in stage 1) by microprocessor 200 when step 3206 in Figure 3B is executed. As a result, the start of the gate interval pulse on signal RICGATE (steps 3206 and 3207) and the generation of the window pulse on
25 signal RICWND in response to a transition on signal DSOUT (step 3208) are delayed an additional 8 μ s with respect to signal SYNC in comparison to the timing of stage 1. As shown in Figure 4(B), the additional delay permits signal VIDEO to lag signal SYNC by as much as 16 μ s without causing line 20 to overlap the gate interval.
30 Stage 2, therefore, enables the window timing to adapt as required to reliably span five cycles of the RIC signal when signal VIDEO lags signal SYNC.

If value CNTVAL is not equal to five (step 350) during stage 2, stage 3 is entered by a return to step 320 after
35 incrementing variable STAGE at step 350. In stage 3, the

procedure executed is the same as during stages 1 and 2 except that the delay provided by delay generator 220 is set to 0 at step 320. Figure 4(C) shows that a delay value of 0 permits the window interval to adapt as required to timing conditions where 5 signal VIDEO leads signal SYNC by as much as 16 μ s.

A successful test of value CNTVAL at step 335 during any of the stages of operation indicates that the delay established for the start of the gate interval signal (delay value of 8 μ s, 16 μ s, or 0 μ s from stage 1, 2, or 3, respectively) is adequate to permit 10 the window interval pulse to move and align correctly with the RIC signal. The delay determined by the routine shown in Figure 3 may be stored by microprocessor 200 and used as needed to determine a data extraction slicing level for data slicer 210 based on the RIC signal. The stored delay value may be used until an 15 event activating the described timing verification procedure occurs.

If none of the stages of operation produce a successful test of value CNTVAL at step 335, a "no auxiliary video data" indication is produced at step 360. The system may respond as 20 required by the particular application. For example, a system might wait and repeat the described procedure either after a predetermined delay or following an event such as a channel change.

Although the invention has been described in the 25 context of closed caption data, the invention is also applicable to other forms of auxiliary video data, e.g. teletext. In the case of other forms of data, the system may require certain modifications. For example, the teletext standard permits teletext data to appear on a number of video lines, e.g. lines 17 to 20. Thus, for a teletext 30 system, signal LINE shown in Figure 2 may have to be generated by means other than the above-described line counter. In addition, auxiliary video data in lines other than line 21 may exhibit timing errors with respect to a horizontal PLL signal that are greater in magnitude than those discussed above. For other 35 forms of auxiliary video, it may be necessary, therefore, to change

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the delay values used in stages 1 through 3 of the operation depicted in Figures 3A and 3B. Alternatively, the number of stages of operation could be changed to add or delete delay values as required.

5 The operation of the disclosed system may be modified in other ways to accommodate alternative auxiliary data formats. As an example, if the format of the reference signal (RIC signal in the described embodiment) changes, the disclosed hardware or software can easily be changed to operate correctly
10 with the data format variations. Modifications of this type may include adapting the system for reference signals having characteristics (e.g. amplitude, waveform, frequency) that differ from the described exemplary RIC signal.

Other modifications of the invention may also be
15 evident to one skilled in the art. For example, hardware may be used to implement functions, e.g. control functions, that are described above and shown in Figure 3 as being performed by execution of software in microprocessor 200. Alternatively, functions shown as separate hardware blocks in Figure 2, e.g.
20 delay generation, pulse generation, counting, may be incorporated into the operations performed by microprocessor 200.

These and other modifications are intended to be within the scope of the invention as defined by the following claims.

CLAIMS:

1. In a system for processing a video signal including
5 an auxiliary information component occurring during at least one of
a plurality of periodic horizontal line intervals of said video signal,
said auxiliary information component including a reference
component exhibiting a periodically varying amplitude, apparatus
comprising:

10 means responsive to said video signal for establishing a
threshold level related to said amplitude of said reference
component during a control interval defined by a control signal, and
for providing at an output of said apparatus an output signal having
a first value when said video signal exceeds said threshold level
15 and having a second value when said video signal is less than said
threshold level; and

means for generating said control signal such that the
timing of said control signal can be adjusted with respect to said
reference component to cause said control interval to encompass a
20 substantially integral number of cycles of said periodically varying
amplitude of said reference component.

2. The apparatus of Claim 1, wherein said control signal
generating means comprises:

25 means responsive to said video signal for providing a
count of said periodic amplitude variations of said reference
component that occur during said control interval; and

means coupled to said count providing means and
responsive to a synchronizing signal indicating a start time of said
30 horizontal line intervals expected to include said auxiliary
information component for modifying a timing relationship of said
control interval to said start time until said count indicates that said
substantially integral number of cycles of said reference component
occurred during said control interval.

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3. The apparatus of Claim 2, wherein said timing relationship modifying means includes means for evaluating said count.

5 4. The apparatus of Claim 3, wherein said count evaluating means comprises a microprocessor.

5. The apparatus of claim 1, wherein said control signal generating means comprises:

10 means for establishing a window interval beginning in response to a start signal and having a duration substantially equal to said control interval;

means for generating said start signal in response to a first signal transition of said video signal crossing said threshold 15 level during an enable interval;

means responsive to a synchronizing signal indicating the beginning of said horizontal line interval containing said auxiliary information component for establishing said enable interval such that said enable interval begins a variable delay after 20 said horizontal line intervals begin; and

means for modifying said variable delay until said window interval spans said substantially integral number of cycles of said periodically varying amplitude of said reference component.

25 6. The apparatus of claim 5, wherein said variable delay modifying means comprises

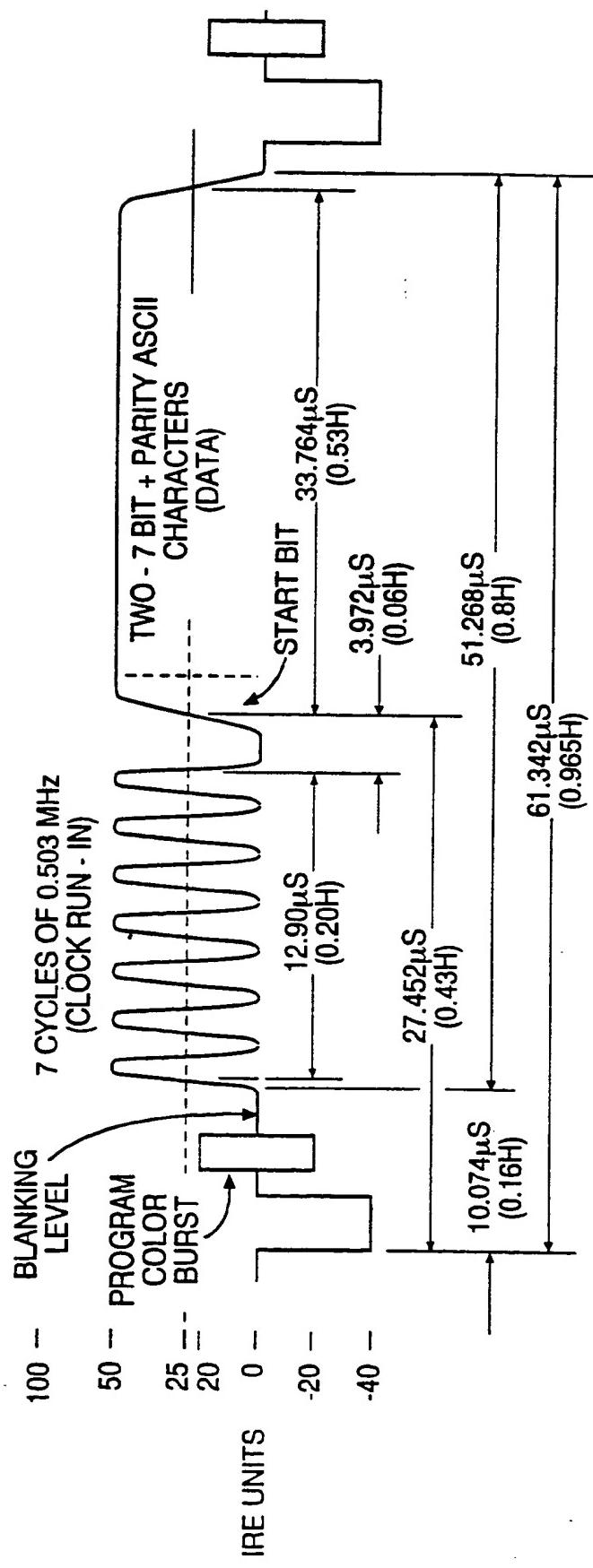
means responsive to said video signal for providing a count of said periodic amplitude variations that occur during said window interval; and

30 means for evaluating said count.

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7. The apparatus of claim 1, wherein
said video signal is subject to exhibiting a lack of said
auxiliary information component during a horizontal line interval
5 expected to include said auxiliary information component; and
said control signal generating means generates a second
control signal in response to detecting said lack of said auxiliary
information component.

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**FIG. 1**

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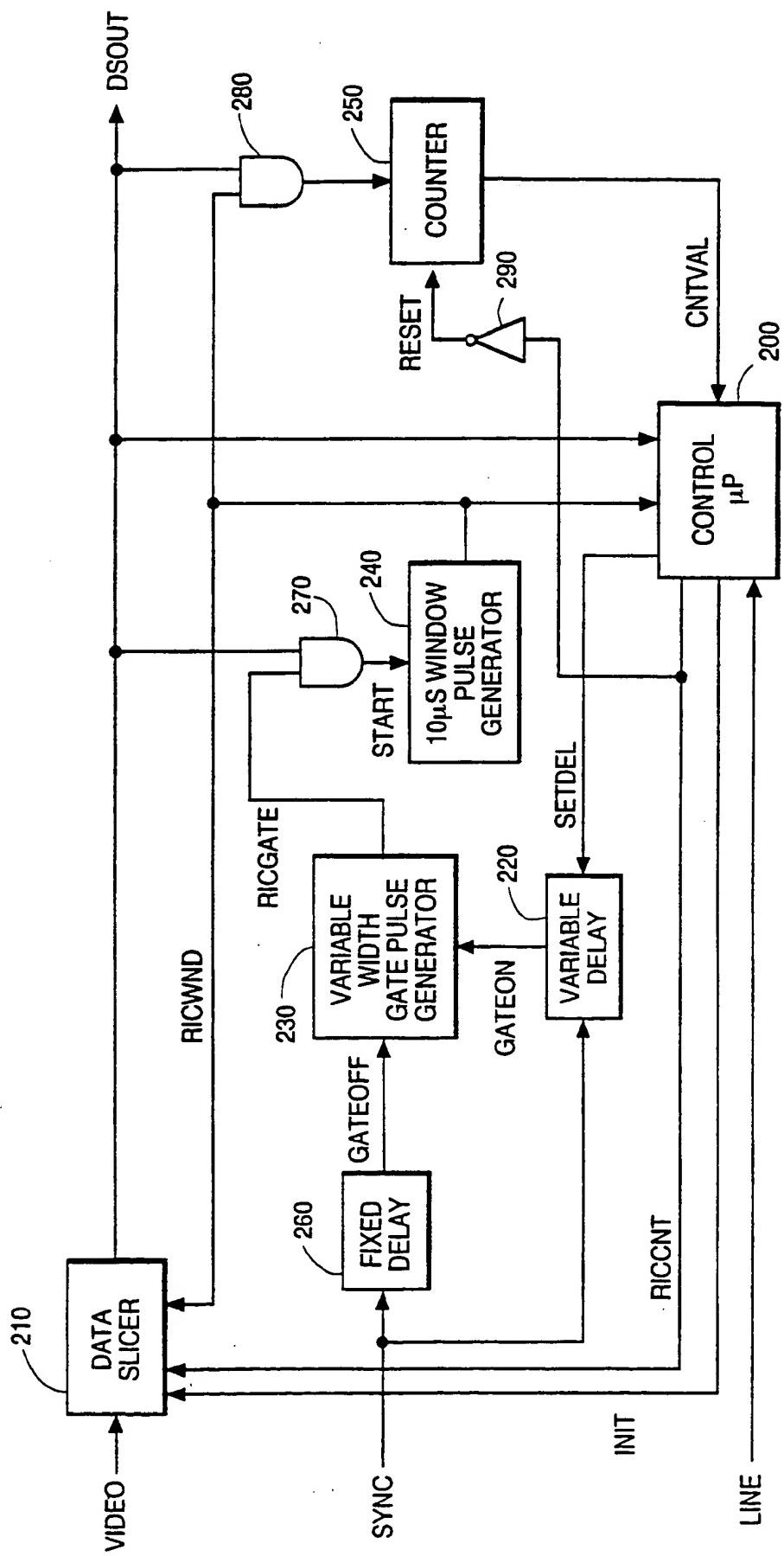


FIG. 2

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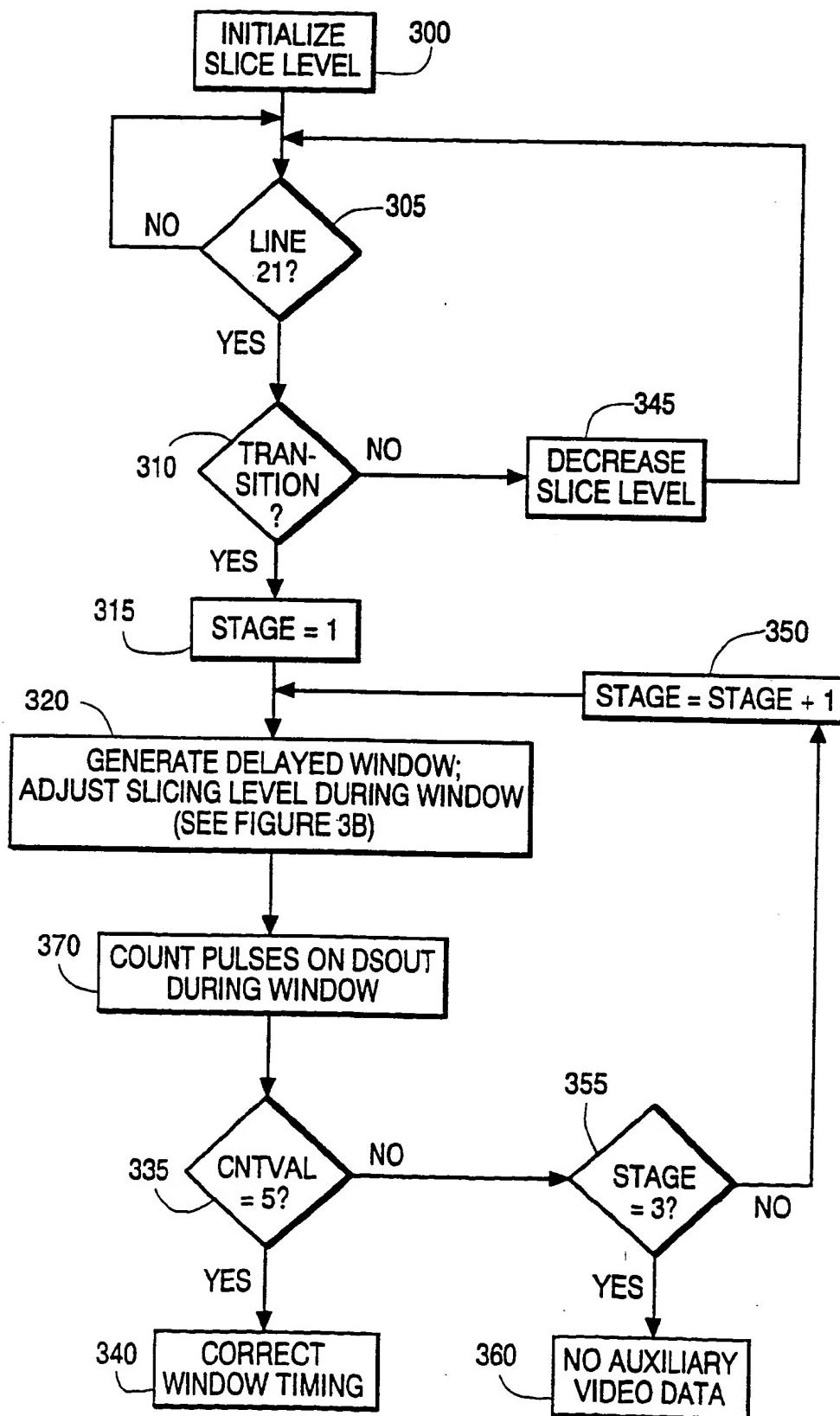
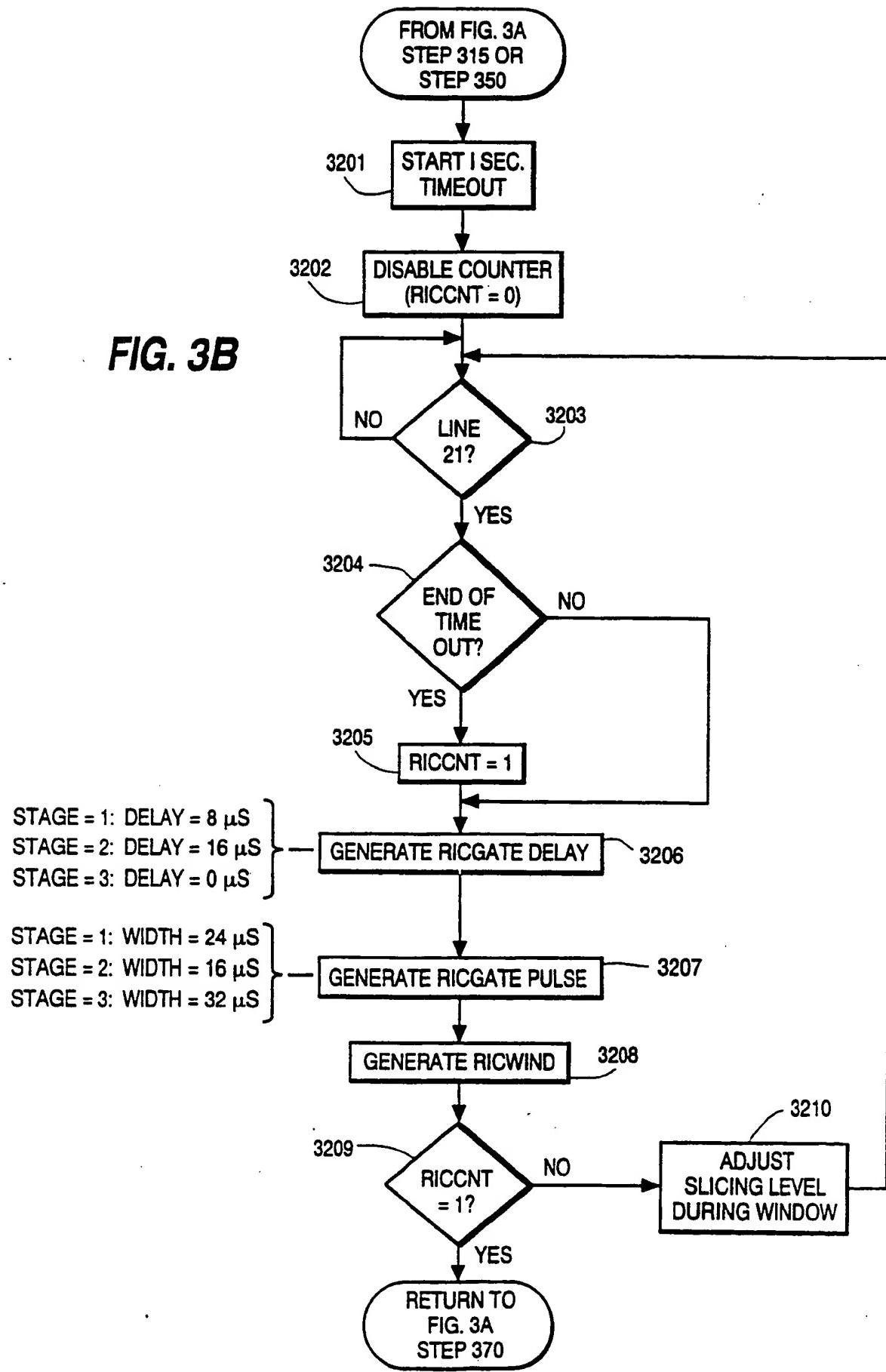
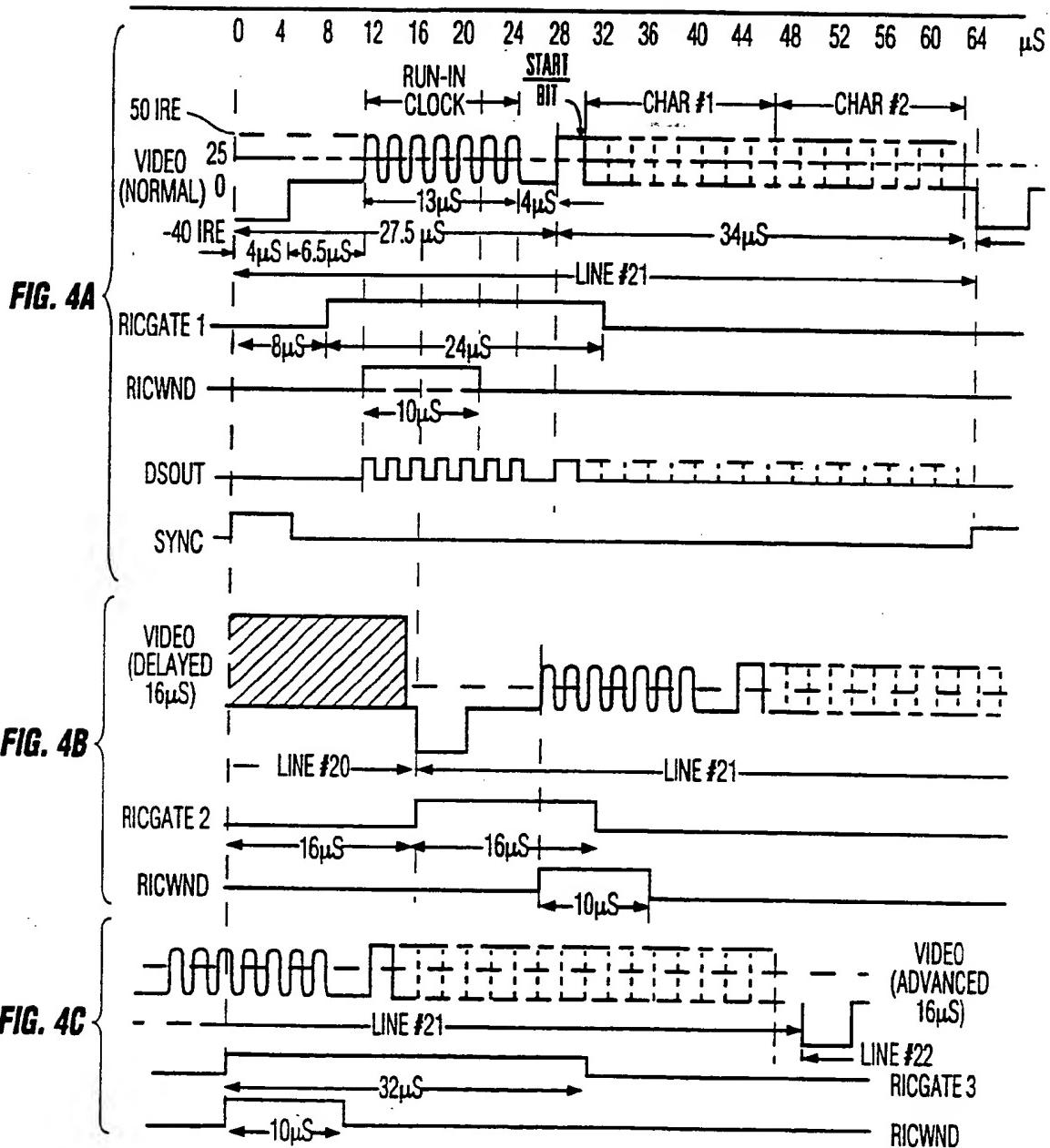
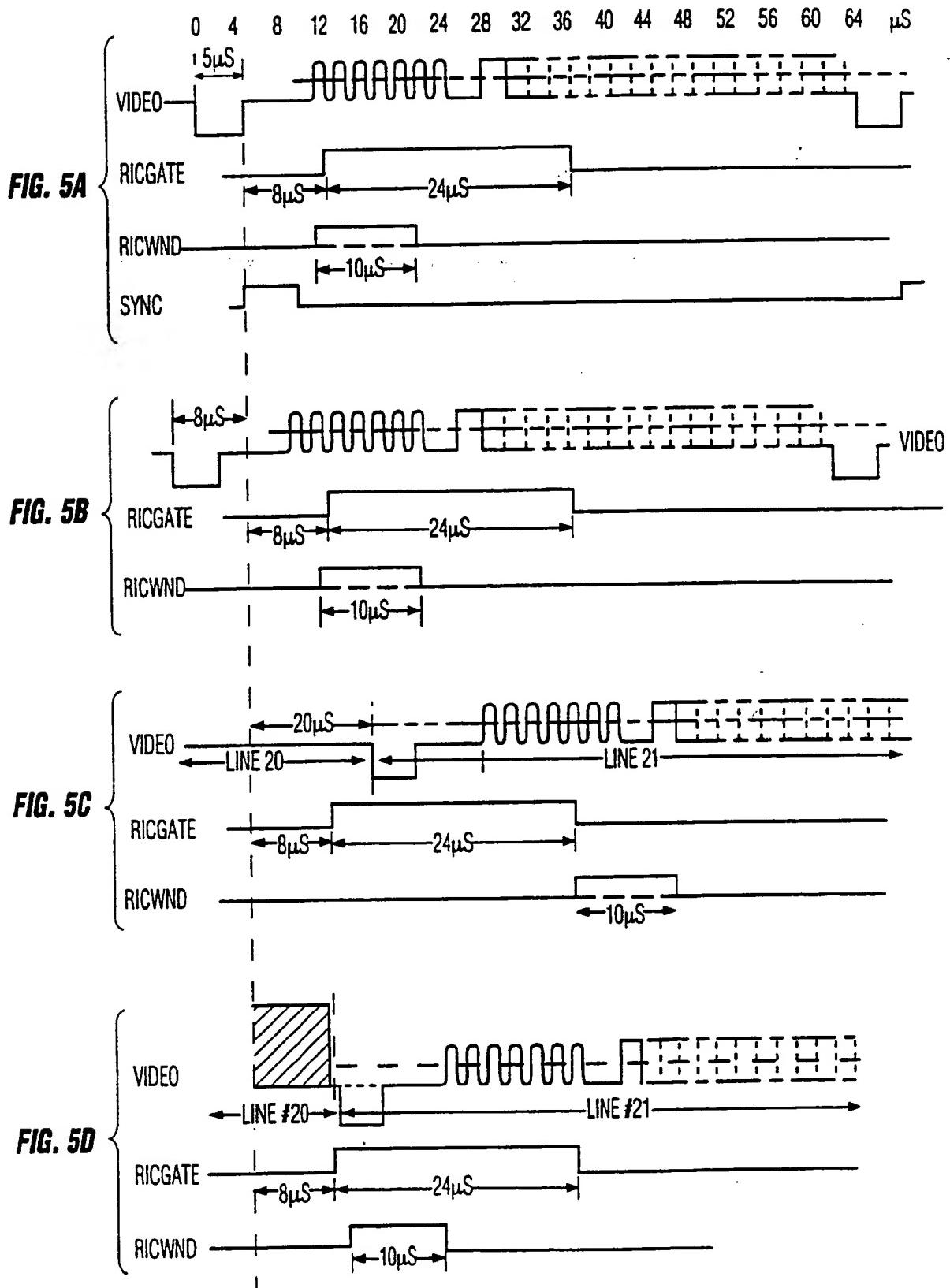


FIG. 3A

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INTERNATIONAL SEARCH REPORT

International Application No

PCT/US 93/00825

I. CLASSIFICATION OF SUBJECT MATTER (if several classification symbols apply, indicate all)⁶

According to International Patent Classification (IPC) or to both National Classification and IPC

Int.Cl. 5 H04N7/00

II. FIELDS SEARCHED

Minimum Documentation Searched⁷

Classification System	Classification Symbols
Int.Cl. 5	H04N

Documentation Searched other than Minimum Documentation
to the Extent that such Documents are Included in the Fields Searched⁸III. DOCUMENTS CONSIDERED TO BE RELEVANT⁹

Category ¹⁰	Citation of Document, ¹¹ with indication, where appropriate, of the relevant passages ¹²	Relevant to Claim No. ¹³
A	US,A,4 318 128 (SAUVANET) 2 March 1982 see the whole document ---	1
A	EP,A,0 421 897 (SGS-THOMSON MICROELECTRONICS S.A.) 10 April 1991 see column 1, line 1 - column 2, line 27 see column 4, line 23 - column 5, line 47; figures 1-4 ---	1
A	US,A,4 667 235 (NOZOE ET AL.) 19 May 1987 see column 9, line 21 - column 11, line 9; figures 12-13 -----	1

¹⁰ Special categories of cited documents :

- ^{"A"} document defining the general state of the art which is not considered to be of particular relevance
- ^{"E"} earlier document but published on or after the international filing date
- ^{"L"} document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- ^{"O"} document referring to an oral disclosure, use, exhibition or other means
- ^{"P"} document published prior to the international filing date but later than the priority date claimed

^{"T"} later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention^{"X"} document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step^{"Y"} document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.^{"&"} document member of the same patent family

IV. CERTIFICATION

Date of the Actual Completion of the International Search

27 MAY 1993

Date of Mailing of this International Search Report

07.06.93

International Searching Authority

EUROPEAN PATENT OFFICE

Signature of Authorized Officer

VERLEYE J.

ANNEX TO THE INTERNATIONAL SEARCH REPORT
ON INTERNATIONAL PATENT APPLICATION NO.

US 9300825
SA 70381

This annex lists the patent family members relating to the patent documents cited in the above-mentioned international search report.
The members are as contained in the European Patent Office EDP file on
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		EP-A,B	0022723	21-01-81
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		JP-A-	3127576	30-05-91
		US-A-	5136382	04-08-92
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		GB-A,B	2164812	26-03-86

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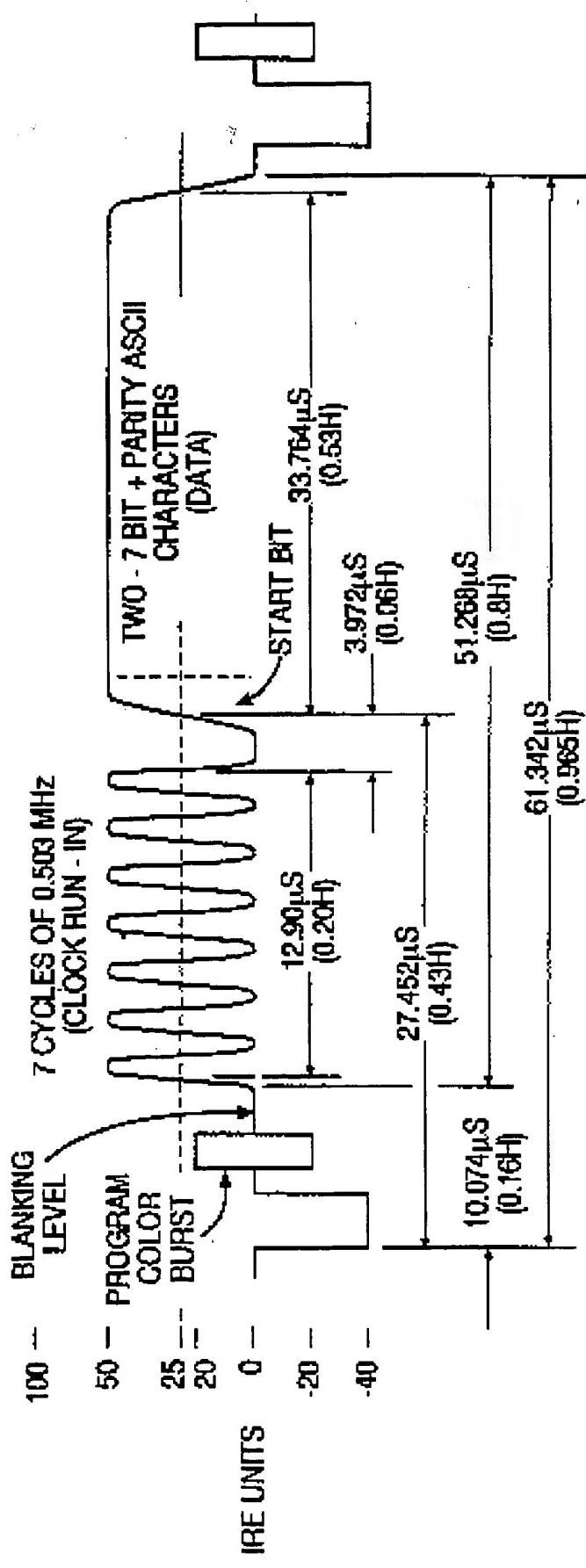


FIG. 1

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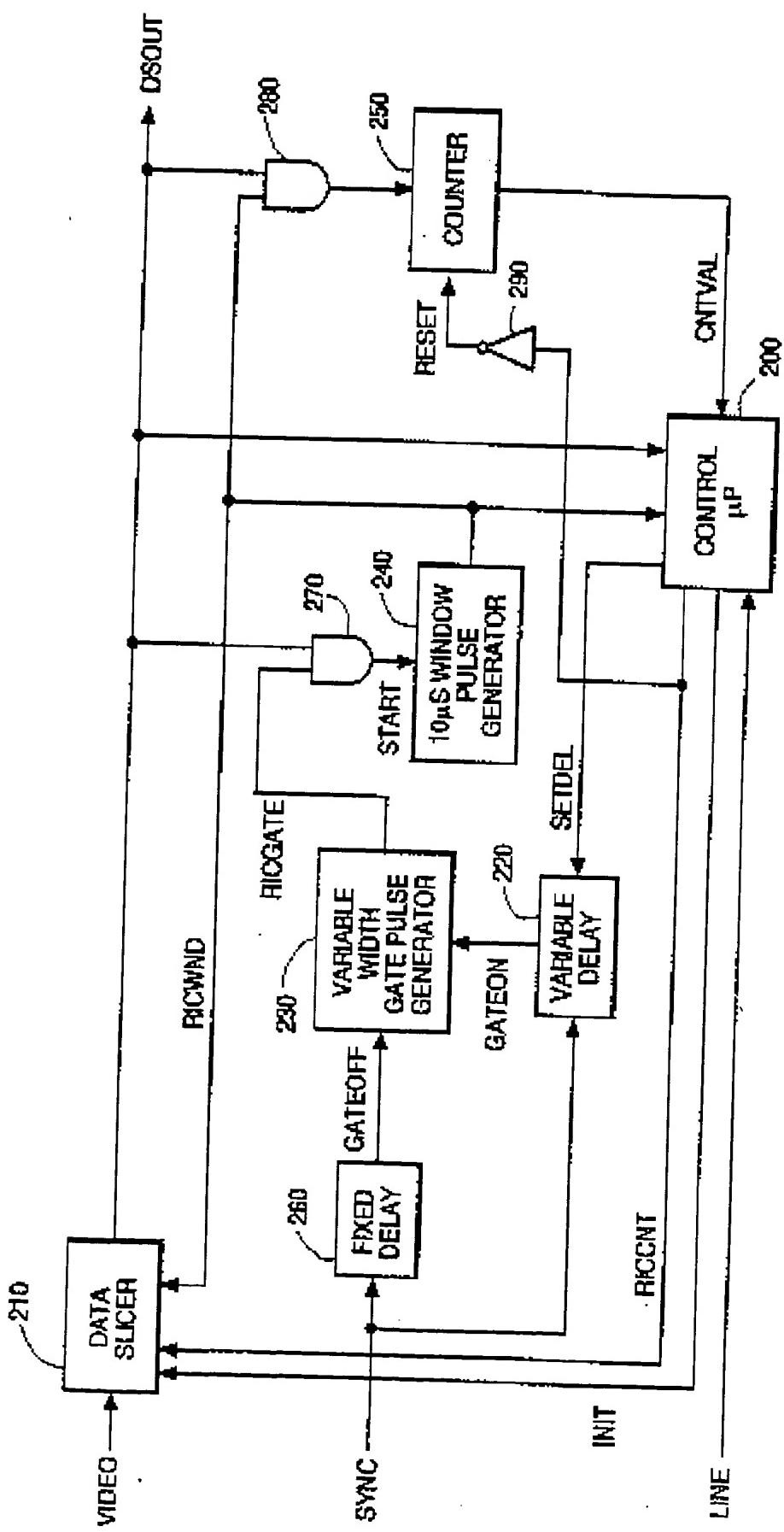


FIG. 2

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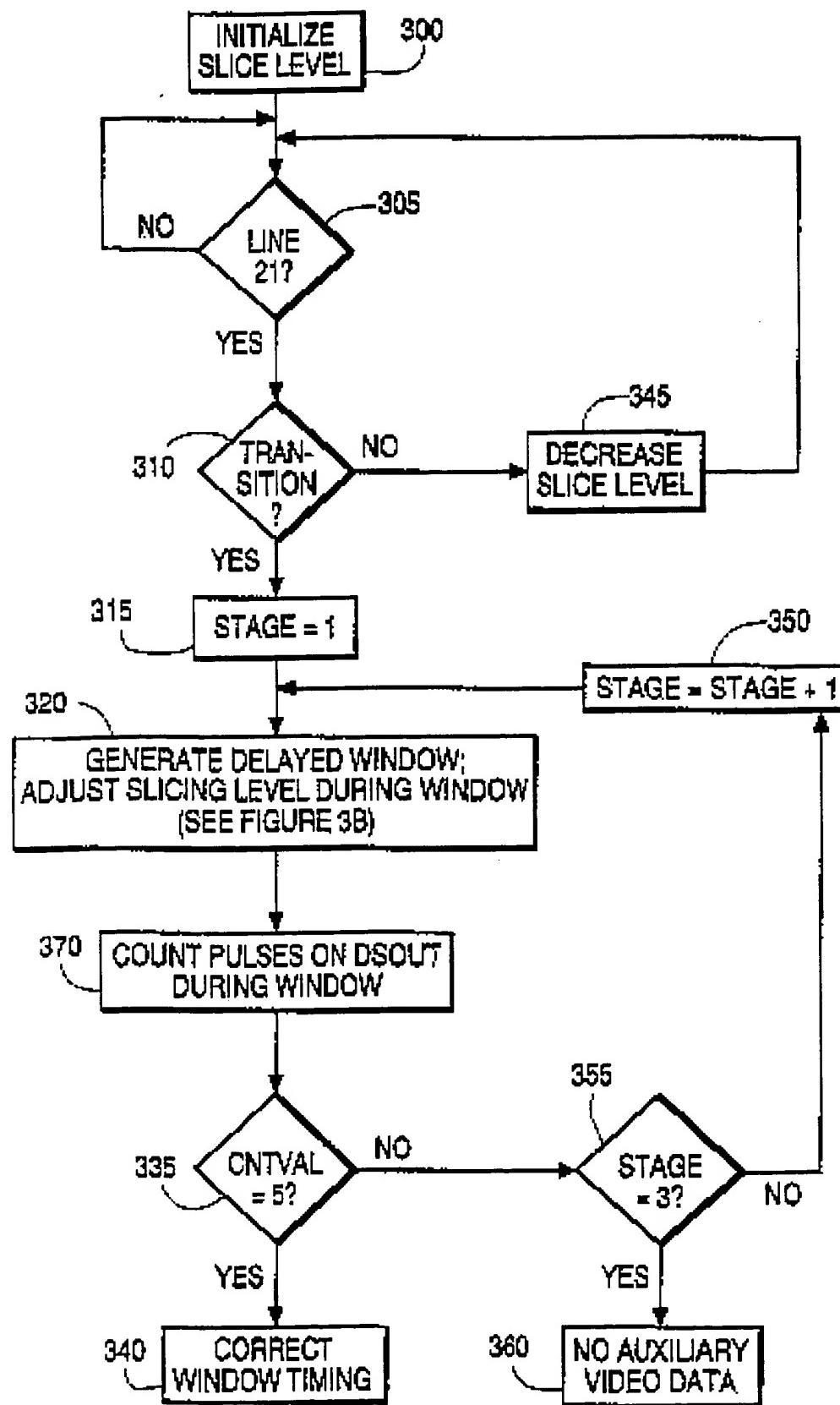
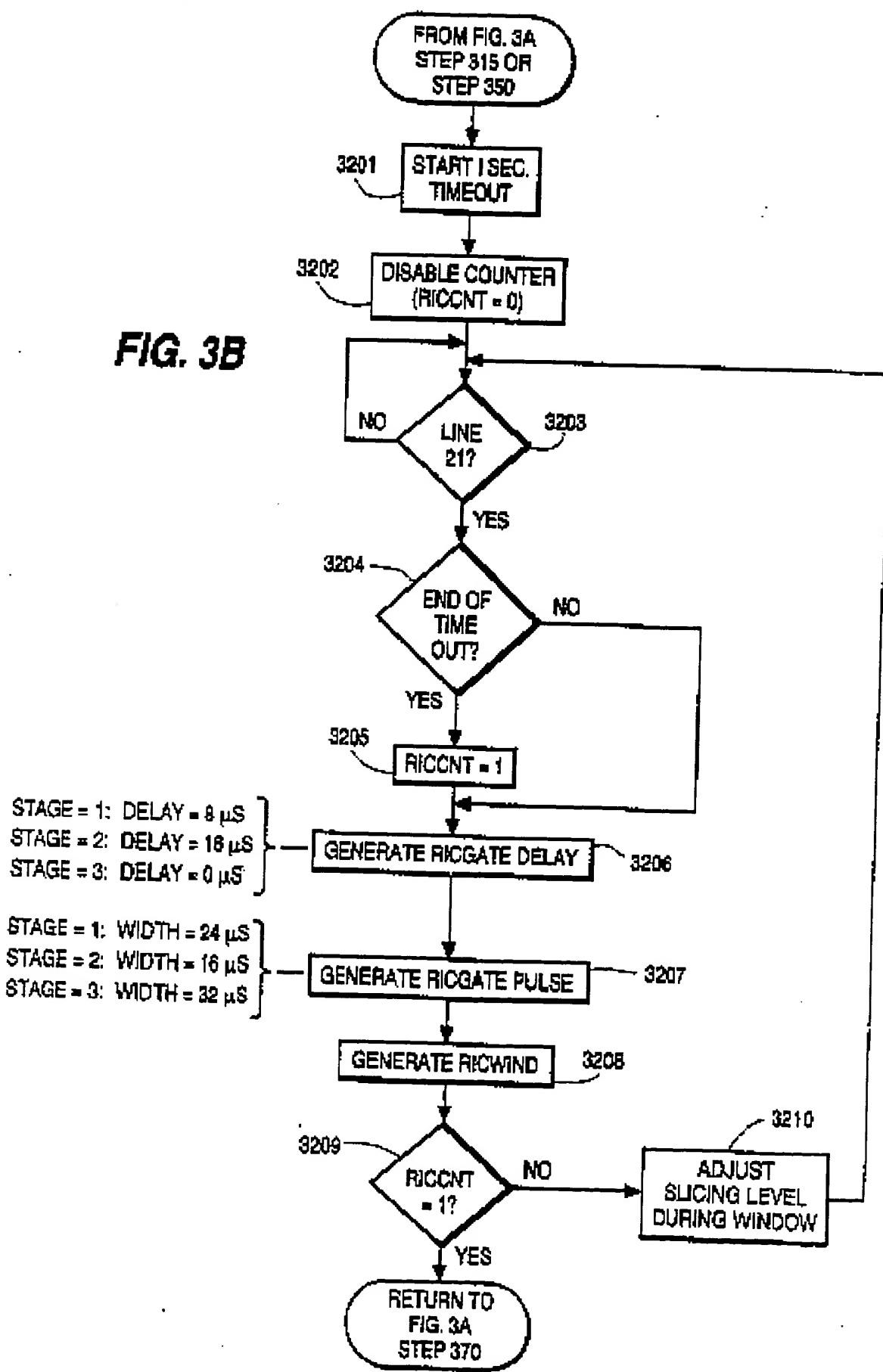
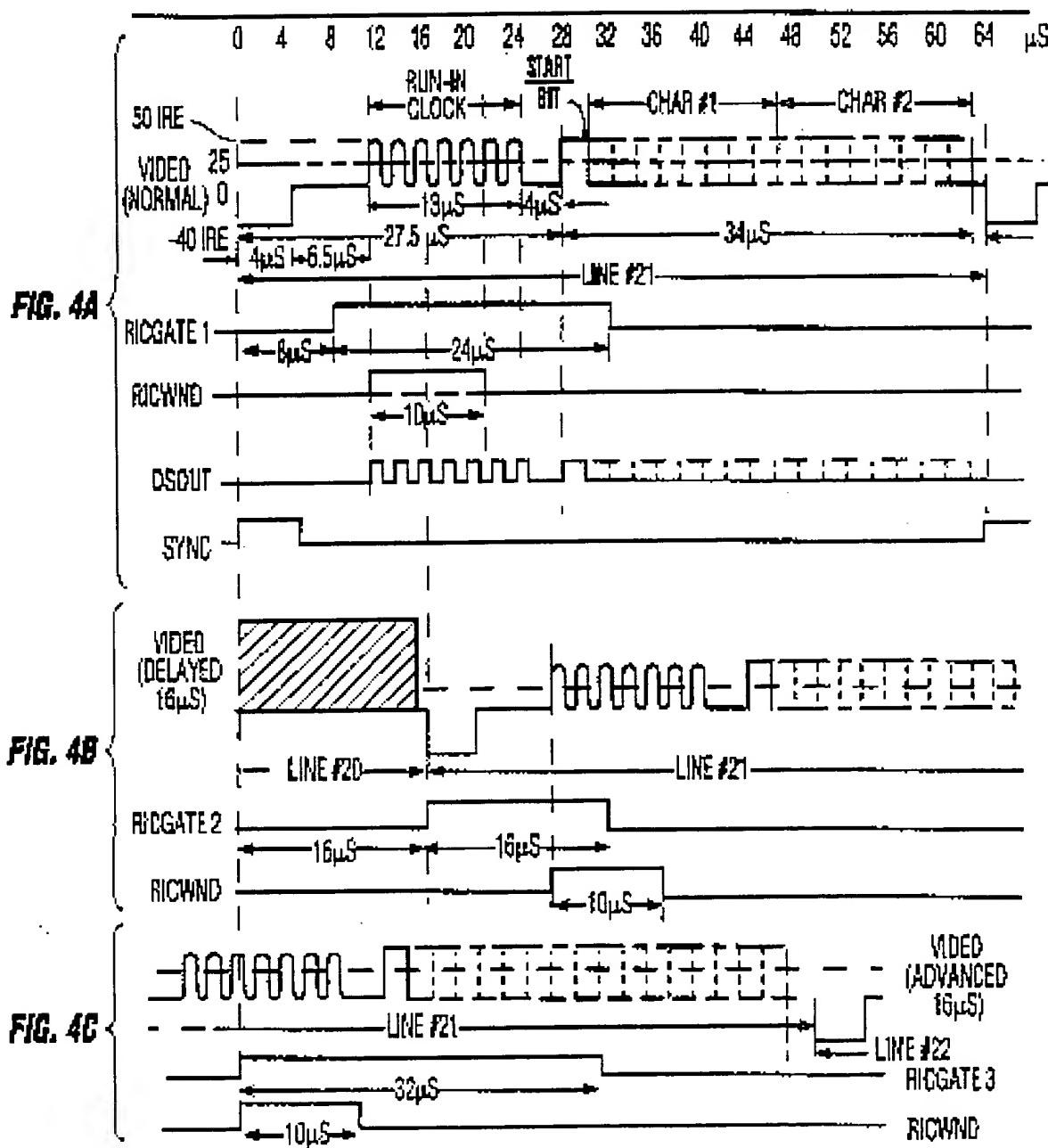


FIG. 3A

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